

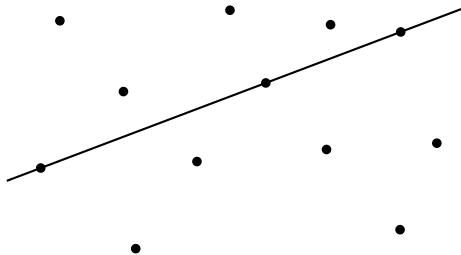
Arrangements and Duality

Computational Geometry

Lecture 11: Arrangements and Duality

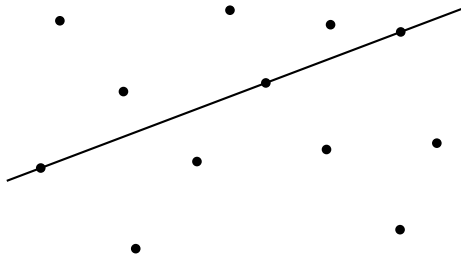
Three Points on a Line

Question: In a set of n points, are there 3 points on a line?



Three Points on a Line

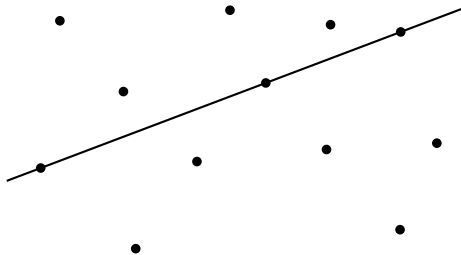
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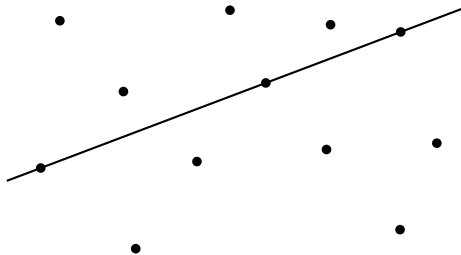


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Faster algorithm: uses **duality** and **arrangements**

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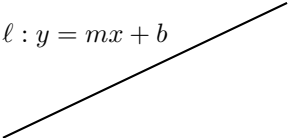


Naive algorithm: tests all triples in $O(n^3)$ time

Faster algorithm: uses **duality** and **arrangements**

Note: other motivation in chapter 8 of the book

Duality

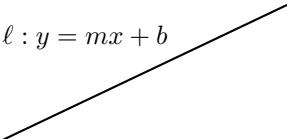
$$\ell : y = mx + b$$


- $p = (p_x, p_y)$

Note:

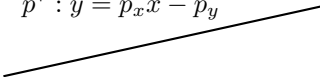
Duality

primal plane

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$$\bullet p = (p_x, p_y)$$

dual plane

$$p^* : y = p_x x - p_y$$


$$\bullet \ell^* = (m, -b)$$

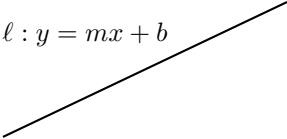
point $p = (p_x, p_y) \mapsto$ line $p^* : y = p_x x - p_y$

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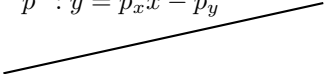
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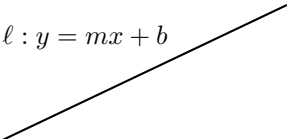
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Note: self inverse $(p^*)^* = p, (\ell^*)^* = \ell$

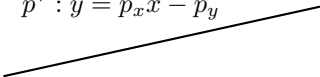
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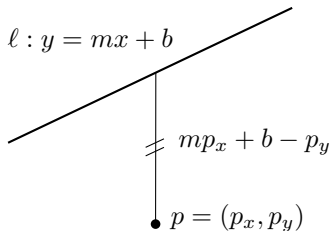
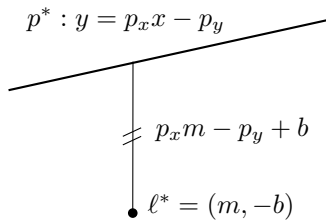
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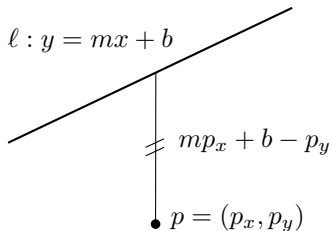
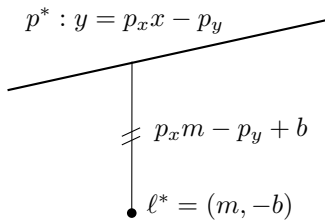
Note: does not handle vertical lines

Duality

primal planedual plane

Duality preserves vertical distances

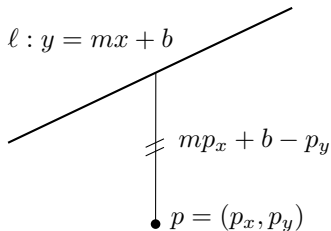
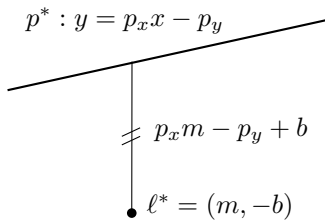
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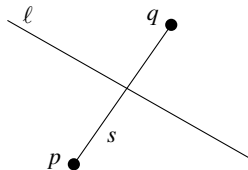
\Rightarrow incidence preserving: $p \in \ell$ if and only if $\ell^* \in p^*$

\Rightarrow order preserving: p lies below ℓ if and only if ℓ^* lies below p^*

Duality

It can be applied to other objects, like segments

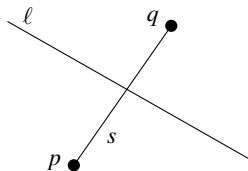
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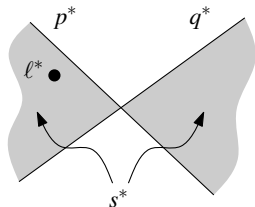
Duality

It can be applied to other objects, like segments

primal plane



dual plane



The dual of a segment is a double wedge

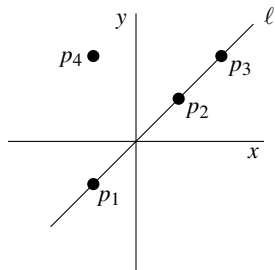
Question: What line would dualize to a point in the right part of the double wedge?

Usefulness of Duality

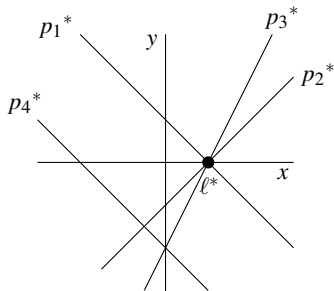
Why use duality? It gives a new perspective!

Detecting **three points on a line** dualizes to detecting **three lines intersecting in a point**

primal plane



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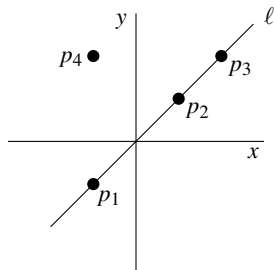


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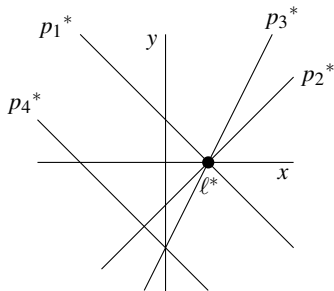
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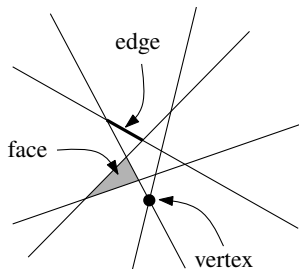


Next we use **arrangements**

Arrangements of Lines

Arrangement $\mathcal{A}(L)$: subdivision induced by a set of lines L

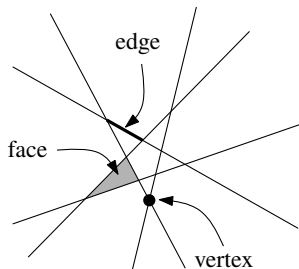
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- arrangements consist of other geometric objects too, like line segments, circles, higher-dimensional objects



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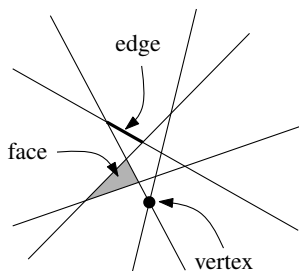
Arrangements of Lines

Combinatorial Complexity:

- $\leq n(n-1)/2$ vertices
- $\leq n^2$ edges
- $\leq n^2/2 + n/2 + 1$ faces:
add lines incrementally

$$1 + \sum_{i=1}^n i = n(n+1)/2 + 1$$

- equality holds in *simple* arrangements



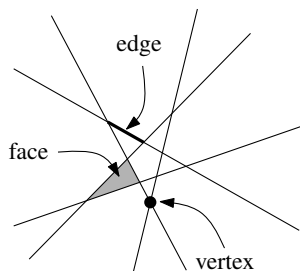
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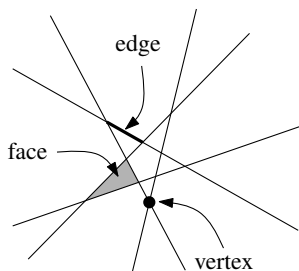
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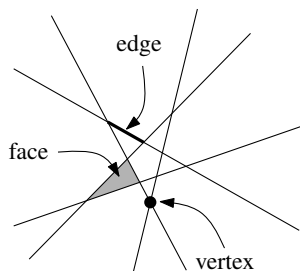
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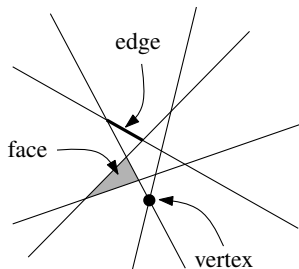
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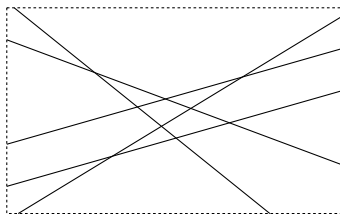
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Overall $O(n^2)$ complexity



Constructing Arrangements

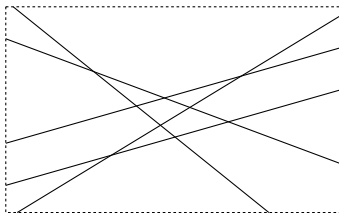
Goal: Compute $\mathcal{A}(L)$ in bounding box in DCEL representation



- plane sweep for line segment intersection:
 $O((n+k)\log n) = O(n^2 \log n)$
- faster: incremental construction

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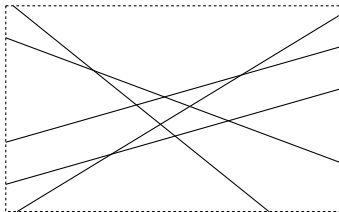
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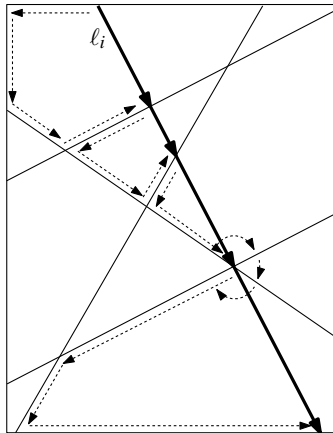
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Incremental Construction



Algorithm CONSTRUCTARRANGEMENT(L)

Input. Set L of n lines

Output. DCEL for $\mathcal{A}(L)$ in $\mathcal{B}(L)$

1. Compute bounding box $\mathcal{B}(L)$
2. Construct DCEL for subdivision induced by $\mathcal{B}(L)$
3. **for** $i \leftarrow 1$ **to** n
4. **do** insert l_i

Incremental Construction

Algorithm CONSTRUCTARRANGEMENT(L)

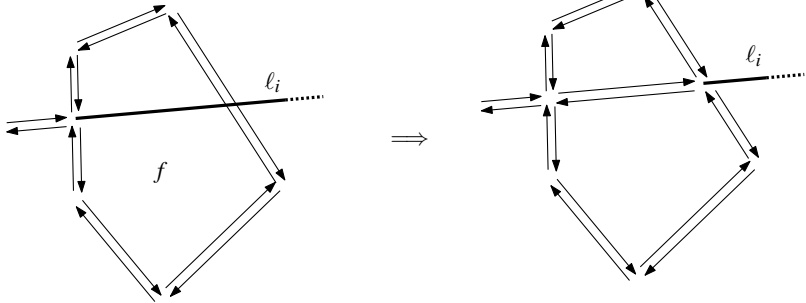
Input. A set L of n lines in the plane

Output. DCEL for subdivision induced by $\mathcal{B}(L)$ and the part of $\mathcal{A}(L)$ inside $\mathcal{B}(L)$, where $\mathcal{B}(L)$ is a suitable bounding box

1. Compute a bounding box $\mathcal{B}(L)$ that contains all vertices of $\mathcal{A}(L)$ in its interior
2. Construct DCEL for the subdivision induced by $\mathcal{B}(L)$
3. **for** $i \leftarrow 1$ **to** n
4. **do** Find the edge e on $\mathcal{B}(L)$ that contains the leftmost intersection point of ℓ_i and \mathcal{A}_i
5. $f \leftarrow$ the bounded face incident to e
6. **while** f is not the unbounded face, that is, the face outside $\mathcal{B}(L)$
7. **do** Split f , and set f to be the next face intersected by ℓ_i

Incremental Construction

Face split:



Incremental Construction

Runtime analysis:

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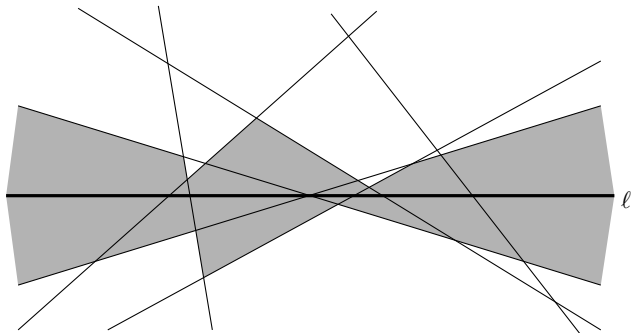
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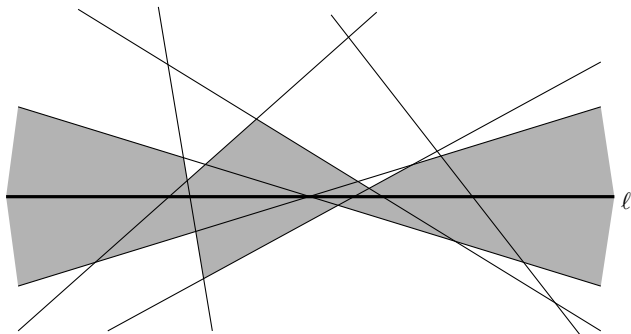
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The **zone** of a line ℓ in an arrangement $\mathcal{A}(L)$ is the set of faces of $\mathcal{A}(L)$ whose closure intersects ℓ



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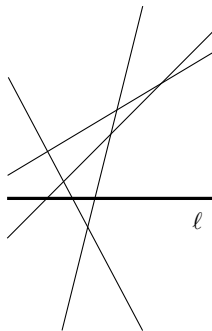
Theorem: The complexity of the zone of a line in an arrangement of m lines is $O(m)$

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- We can assume ℓ horizontal and no other line is horizontal
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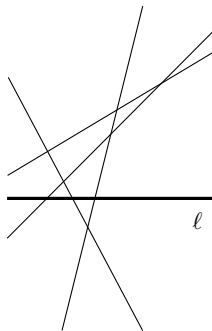


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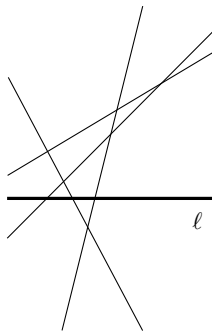


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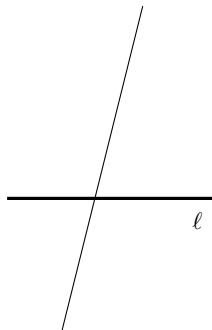


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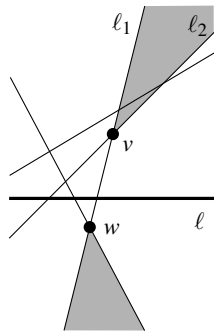


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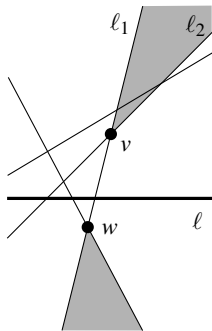


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 - $m > 1$: only at most 3 new edges if l_1 is unique, at most 5 if l_1 is not unique
 $5(m - 1) + 5 = 5m$



Incremental Construction

Run time analysis:

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In total $O(n^2)$

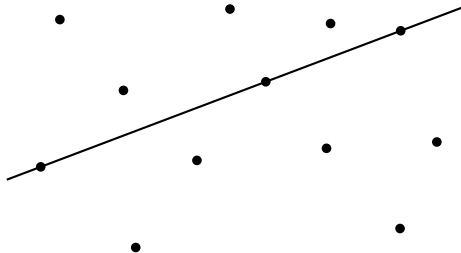
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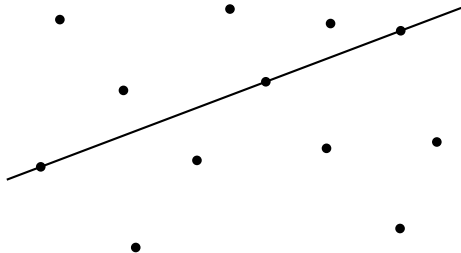
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3 Points on a Line



3 Points on a Line



Algorithm:

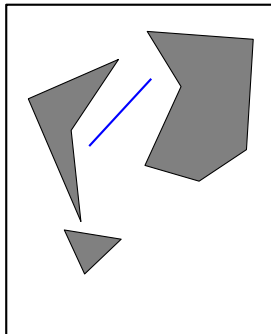
- run incremental construction algorithm for dual problem
- stop when 3 lines pass through a point

Run time: $O(n^2)$

Example: Motion Planning

Where can the rod move by translation (no rotations) while avoiding obstacles?

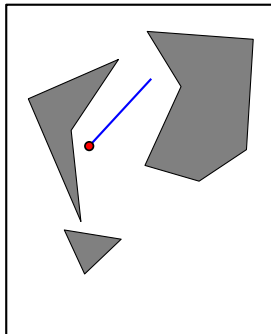
- pick a **reference point**:
lower end-point of rod
- shrink rod to a point,
expand obstacles accordingly:
locus of **semi-free placements**
- reachable configurations:
cell of initial configuration in
arrangement of line segments



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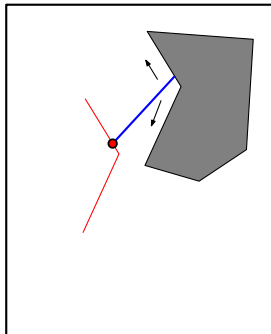
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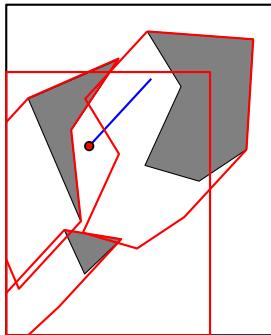
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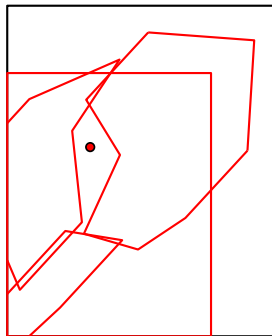
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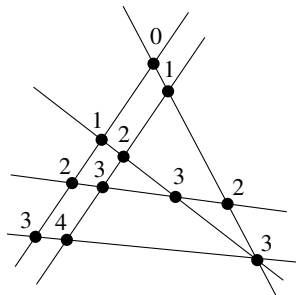
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k-levels in Arrangements

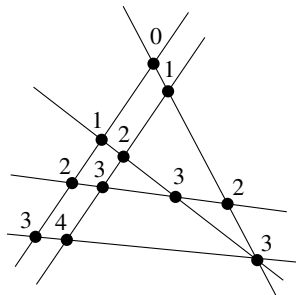
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Open problem: What is the complexity of k-levels?

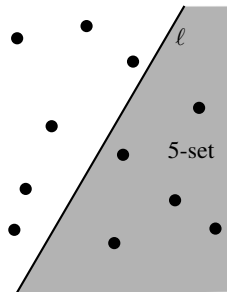


k-levels in Arrangements

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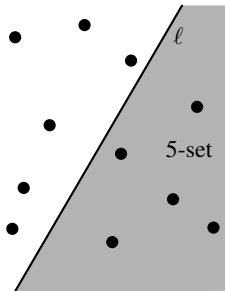
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Known bounds:

- Erdős et al. '73:
 $\Omega(n \log k)$ and $O(nk^{1/2})$
- Dey '97: $O(nk^{1/3})$



k-levels in Arrangements

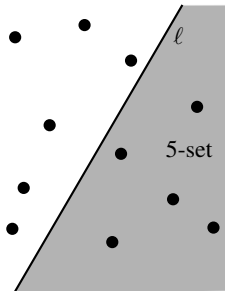
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Three dimensions

In 3D, we have point-plane duality; lines dualize to other lines

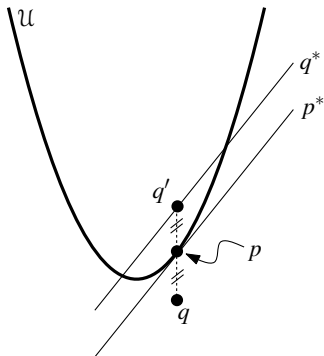
An arrangement induced by n planes in 3D has complexity $O(n^3)$

Deciding whether a set of points in 3D has four or more co-planar points can be done in $O(n^3)$ time (dualize and construct the arrangement)

More Duality

A geometric interpretation:

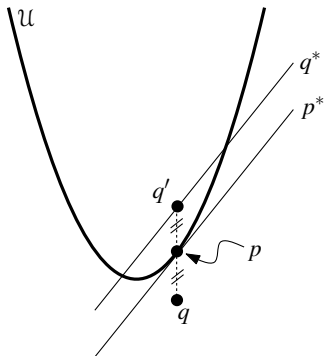
- parabola $\mathcal{U} : y = x^2/2$
- point $p = (p_x, p_y)$ on \mathcal{U}
- derivative of \mathcal{U} at p is p_x , i.e., p^* has same slope as the tangent line
- the tangent line intersects y-axis at $(0, -p_x^2/2)$
- $\Rightarrow p^*$ is the tangent line at p



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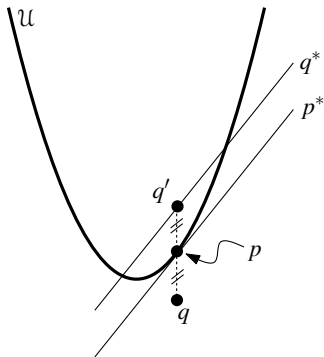
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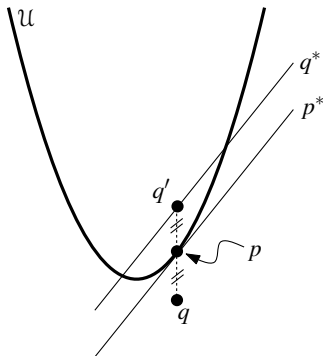
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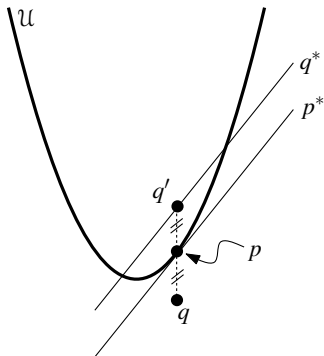
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Summary

Duality is a useful tool to reformulate certain problems on points in the plane to lines in the plane, and vice versa

Dualization of line segments is especially useful

Arrangements, zones of lines in arrangements, and levels in arrangements are useful concepts in computational geometry

All of this exists in three and higher dimensional spaces too