

# Strictification of Lazy Functions

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## Abstract

This paper describes a transformation from lazy functions into efficient non-lazy ones. The functions we study perform multiple traversals over a data structure. Our transformation performs a global analysis of the calling structure of a set of mutually recursive lazy-functions in order to transform them into sets of functions which must be called in sequence. Many of the resulting functions can be eliminated by the optimizations presented in this paper. We present measurements that show that transformed and optimized functions allow efficient incremental execution. The paper contains examples that were automatically constructed with a generator of incremental functional programs.

## 1 Introduction

One of the more intricate parts of the world of functional programming deals with the construction of so-called circular programs, with the program *repm* of Bird acting as the canonical representative of this class [Bir84]. For almost everyone, when first introduced to such programs, it takes a while before (s)he actually is convinced that such a program may work indeed as claimed by their authors. It is the use of lazy evaluation which does the trick.

For those who have not seen such programs before, we present here again the example of [Bir84]. The goal of this program is to compute a binary tree with integers in the leaves, which has the same shape as the argument tree, but with all leaves replaced by the minimal value in the original tree.

$$\begin{aligned} \text{repm } t &= r \\ \text{where } (r, m) &= \text{repm}' t m \\ \text{repm}' (\text{Fork } l r) m &= (\text{Fork } lr rr), lm \text{ min } rm) \\ \text{where } (lr, lm) &= \text{repm}' lt \\ (rr, rm) &= \text{repm}' rt \\ \text{repm}' (\text{Leaf } v) m &= (\text{Leaf } m, v) \end{aligned}$$

The curious thing here is that part of the result of the initial call to *repm'*, i.e. *m*, is also passed as an argument to *repm'*.

For those who are well acquainted with attribute grammars such dependencies come as no surprise, they are well used to thinking in terms of setting up equations between attributes,

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and letting the system worry about the order in which the computations are actually scheduled. It has furthermore been noticed by [KS87, Joh87] that there exists a direct translation from attribute grammars into this class of circular programs. Those acquainted with catamorphisms will furthermore recognise a catamorphism which returns a higher order type in the above program [MFP91].

In recent years we have been interested in the incremental evaluation of (higher order) attribute grammars [VSK91, SV91, PSV92, Pen94]. The main aspect of the method being used is that attribute grammars are transformed into large sets of mutually recursive *strict* functions, the calls to which are being cached in order to avoid unnecessary reevaluations. The fact that the arguments to these functions can be evaluated before the call, without changing the termination properties, makes the resulting evaluators efficient and simple, and thus there is no need anymore to implement the much more complicated, and much less efficient, caching of lazy functions [Hug85].

In this paper we present the techniques we present our techniques in the setting of functional languages and transformations thereof. One might foresee that these methods find their way into a compiler, as has happened with techniques like deforestation and virtual data structures [Wad90, SdM93].

It is relatively easy to see how the program *repmin'* might be splitted into two functions: one that computes the minimal value of all the leaves, and one that constructs the resulting tree. In this way the circular dependency is broken. In section 2 we introduce an example program that can not be splitted so easily because the circular dependencies not only occur at the top level call, but also inside the recursive calls.

In section 3 we show how, after analysing the dependencies between the function arguments, the functions can be transformed into sequences of functions, which have to be called one after the other for each subtree. For this transformation to work we introduce so-called *bindings*: a kind of explicitly constructed environment part of the closure that would otherwise have been constructed.

When looking at the set of functions constructed in this way we will see that many functions actually do very little work. Thus we show in section 4 how by unfolding some definitions, several of the generated functions become superfluous, and may be removed from the program.

In section 5 we finally show that certain nodes of the trees have lost their semantic meaning for certain calls of functions; in order to get a better caching behaviour the program may again be transformed so that such nodes will no longer have to occur in the trees. Finally we have reached the situation in which only relevant calls remain, thus guaranteeing an optimal use of the function cache, in which we have a canonical representation for each subcomputation. We demonstrate the effectiveness of our approach by presenting a few results of re-evaluations of functions generated by our system.

In section 6 we finally present some conclusions.

## 2 The Example

Our approach will be introduced through an example. We present a program that generates code for a simple language called BLOCK. This language deals with the *scope* of variables in a *block structured language*. A variable from a global scope is visible in a local scope only if is not hidden by a variable with the same name in the local scope. A program in BLOCK is

a list of *declarations* (such as `dcl a`), *statements* (such as `use a`) and *blocks*, where a block is also a list of declarations, statements and nested blocks. A concrete sentence in this language looks as follows:

```
(use x;dcl x;dcl w;
  (use z;use y ;dcl x;dcl z;use x);
dcl y;use y)
```

where blocks are surrounded by parenthesis. The local usage of  $x$  refers to the local declaration and the global usage of  $x$  refers to the global declaration. The usage of  $y$  and  $z$  refer to their only declaration (global and local respectively).

The structure of the language leads naturally to a two pass compiler: the first pass collects all the declarations of blocks, and the second one actually uses the constructed environment.

The objective of the program is to generate code for a BLOCK program. The code consists of a sequence of three types of instructions: `Enter( $d$ )` which enters a block with  $d$  local declarations; `Leave( $d$ )` which leaves a block with  $d$  local declarations and `Access( $l, d$ )` which accesses the  $d$ 'th variable (*displacement*) of the  $l$ 'th nested block (*level*). The code for example above is:

```
Enter 3, Access 1 0,
  Enter 2, Access 2 1, Access 1 2, Access 2 0, Leave 2,
  Access 1 2, Leave 3
```

The abstract syntax of the language BLOCK is defined by the following recursive data definitions:

```
data Program = P Items
data Items   = NilItems
              | Cons_Items Item Items
data Item    = Block Items
              | Use Name
              | Decl Name
data Name    = Ident STR
```

and the data type for the environment is:

```
data Env = Consenv Name Level Displacement Env
         | Emptyenv
```

The abstract syntax of the generated code is defined by:

```
type Code      = [Instr]      data Instr = Access Level Displacement
type Level     = Int           | Enter Int
type Displacement = Int       | Leave Int
```

Implementing the compiler in a functional language (*e.g.* GOFER) is "straightforward". The complete program is presented in figure 1.

Where the function `access` takes as arguments the environment and the variable being accessed and returns the appropriate instruction.

Observe that this program is a *circular* program (in the sense of [Bir84]), that is, one of the results of a function call is also one of its arguments. This occurs twice in the program: in function `travProgram` with argument/result `dcl` and in the alternative `Block` of function



a recursive data type and the recursion structure of the functions “follows” the structure of their first argument. Each function has several definitions that are distinguished by the constructor used in the first argument. The sub-traversals in the transformed program have as first parameter the same recursive data type as the original traversal.

The strict version is obtained in 5 steps.

1. analysis of dependencies among arguments and results of traversal functions
2. linearization of dependencies
3. definition of interfaces of sub-traversals
4. dealing with interdependencies between sub-traversals
5. generation of GOFER code

The *first* step determines how arguments and results of functions may depend upon each other, and is based on well known attribute grammar analysis techniques [Kas80]. This step builds two kinds of dependencies: those among the arguments and results of one function and those among all arguments and results of all calls occurring in a function body. Once the dependencies are known we can see whether an argument in a call depends on a result in the same call. This is illustrated in figure 2 by the dependency from the result *dcl* of **travItems** to the argument *env*.

The *second* step linearizes the dependencies. This step works on all dependency graphs of all function definitions. This step computes an order in which the arguments and results must be computed. The computed order is compatible with the dependencies from the first step, meaning that if  $x \rightarrow y$  is a dependency from step 1 then  $x$  comes before  $y$  in the order computed in this step. In our example the order computed for **travItems** is *lev, nodi, dcl*, *dcl*, *env, nodo, code*.

The *third* step determines the interfaces of the sub-traversals. Arguments and results of a function are grouped into a sequence of ([argument],[result]) pairs. Each pair will give rise to one sub-traversal function, that computes the [result] from [argument]. For example, for function **travItems**, the constructed sequence consists of two pairs: first (*lev, nodi, dcl*), *dcl*) and then (*env*),*nodo, code*).

The *fourth* step deals with interdependencies among sub-traversals. An example of such an interdependency is the case where an argument of a function is used in more than one sub-traversal. For example consider the parameter *lev* in figure 2. This parameter is needed in first and second sub-traversal of that function. Since for all calls of **travItem** the interface should be the same, the parameter *lev* is passed to first sub-traversal corresponding to **travItem**: it may be that the alternative **Decl** has to be dealt with, in which *lev* is used to extend the list of declarations. If the alternative however is a **Block** the parameter *lev* is actually only used in the second sub-traversal of **travItem**, since that is the one which contains the call to the first sub-traversal for the **Block**.

To handle such interdependencies among sub-traversals this step introduces *bindings*. Bindings contain precisely those values that should be passed from one sub-traversal to the next. They are *constructed* in one traversal —values that should be passed are included— and *deconstructed* in the next so that the values are available for use. Bindings are terms with a structure much like the tree that is being traversed.

Suppose we have  $n$  different, mutually recursive, data types  $T_i$  ( $1 \leq i \leq n$ ) and that we have  $t_i$  traversals on data type  $T_i$ . These traversals have the following types, where  $1 \leq i \leq n$  and  $1 \leq v \leq t_i$

$$\mathbf{trav}_v T_i :: T_i \dots \mathit{inputs} \dots \rightarrow \langle \dots \mathit{outputs} \dots \rangle$$

These functions are augmented with bindings, a change that is reflected in their types. The function for sub-traversal  $v$  for data type  $T_i$  may return binding information for all subsequent sub-traversals, that is to say for sub-traversals  $w$  with  $v + 1 \leq w \leq t_i$ . Besides that, this function may also be passed bindings from all its predecessors, i.e. traversals  $w$  with  $1 \leq w \leq v - 1$ . In other words, the types are changed to:

$$\begin{aligned} \mathbf{trav}_v T_i &:: T_i \dots \mathit{inputs} \dots \rightarrow T_i^{1 \rightarrow v} \rightarrow T_i^{2 \rightarrow v} \rightarrow \dots \rightarrow T_i^{v-1 \rightarrow v} \\ &\rightarrow \langle \dots \mathit{outputs} \dots, T_i^{v \rightarrow v+1}, T_i^{v \rightarrow v+2}, \dots, T_i^{v \rightarrow t_i} \rangle, \end{aligned}$$

where  $T_i^{v \rightarrow w}$  is the type of the binding computed during traversal  $v$  to  $T_i$  and used during traversal  $w$  to  $T_i$ .

We must now determine the constructors for the bindings  $T_i^{v \rightarrow w}$ . Suppose that there are  $n_i$  constructors  $\mathbf{con}_{i,k}$  (where  $1 \leq k \leq n_i$ ) on type  $T_i$ . With each of these constructors we associate a set of so called binding constructors  $\mathbf{con}_{i,k}^{v \rightarrow w}$  on  $T_i^{v \rightarrow w}$  with defining traversal  $v$  ( $1 \leq v \leq t_i - 1$ ) and using traversal  $w$  ( $v + 1 \leq w \leq t_i$ ). In other words, for any type  $T_i$ ,  $1 \leq i \leq n$ , we have  $\frac{1}{2}t_i(t_i - 1)$  associated binding types  $T_i^{v \rightarrow w}$ ,  $1 \leq v < w \leq t_i$ , each with  $n_i$  binding constructors:

$$\begin{aligned} \mathbf{data} T_i^{v \rightarrow w} &= \mathbf{con}_{i,1}^{v \rightarrow w} \dots \\ &| \mathbf{con}_{i,2}^{v \rightarrow w} \dots \\ &\vdots \\ &| \mathbf{con}_{i,n_i}^{v \rightarrow w} \dots \end{aligned}$$

Now that we have set up a framework for bindings, we are finally able to discuss the *shape* of the binding constructors. A binding constructor  $\mathbf{con}_{i,k}^{v \rightarrow w}$  binds objects that are computed in traversal  $v$  of an instance of constructor  $\mathbf{con}_{i,k}$  and that are used in traversal  $w$  of that same node. Binding constructors bind two kinds of objects namely local results and arguments to be used later and *bindings for sons*. In our example, a **Block** node puts a *lev* in a binding, and a **Cons\_Items** node puts the *binding* for each son in a binding.

Bindings may be empty, and most of them probably are. That is to say, the mutual recursive definitions of the bindings is such that for a particular binding, the (infinite) set of all producible terms contains no term that binds a (non-binding) value. The fourth step determines which bindings are guaranteed to be empty and these are not added to the sub-traversals. The bindings added in this step require the definition of extra data types. The bindings induced by our example are:

$$\begin{aligned} \mathbf{data} \mathit{Item}^{1 \rightarrow 2} &= \mathbf{Use}^{1 \rightarrow 2} \\ &| \mathbf{Decl}^{1 \rightarrow 2} \\ &| \mathbf{Block}^{1 \rightarrow 2} \quad \mathit{Int} && \text{-- type(lev)} \\ \mathbf{data} \mathit{Items}^{1 \rightarrow 2} &= \mathbf{NilItems}^{1 \rightarrow 2} \quad \mathit{Int} && \text{-- type(nodo)} \\ &| \mathbf{Cons_Items}^{1 \rightarrow 2} \quad \mathit{Item}^{1 \rightarrow 2} \quad \mathit{Items}^{1 \rightarrow 2} \end{aligned}$$

The *fifth* and final step constructs the GOFER code for the sub-traversals. The code of the transformed program is presented in figure 3.

```

trav1Program (P Items = (code)
  where (dcl0, Items1→2) = trav1Items Items Emptyenv 0 0
        (code, nodo)      = trav2Items Items dcl0 Items1→2)

trav1Items (Cons_Items Item Items) dcli nodi lev = (dcl0, Cons_Items1→2 Item1→2 Items1→2)
  where (dcl0, nodo, Item1→2) = trav1Item Item dcli nodi lev
        (dcl0, Items1→2)      = trav1Items Items dcl0 nodo lev

trav1Items (NilItems) dcli nodi lev = (dcli, NilItems1→2 nodi)

trav2Items (Cons_Items Item Items) env (Cons_Items1→2 Item1→2 Items1→2) = (code1 ++ code2, nodo2)
  where code1 = trav2Item Item env Item1→2
        (code2, nodo2) = trav2Items Items env Items1→2

trav2Items (NilItems) env (NilItems1→2 nodo) = ([], nodo)

trav1Item (Decl name) dcli nodi lev = (Consenv name lev nodi dcli, nodi + 1, Decl1→2)

trav1Item (Use Name) dcli nodi lev = (dcli, nodi, Use1→2)

trav1Item (Block Items) dcli nodi lev = (dcli, nodi, Block1→2 (lev + 1))

trav2Item (Decl name) env Decl1→2 = ([])

trav2Item (Use name) env Use1→2 = (code)
  where code = [access env name]

trav2Item (Block Items) env (Block1→2 lev) = ([Enter nodo] ++ code1 ++ [Leave nodo])
  where (dcl0, Items1→2) = trav1Items Items env 0 lev
        (code1, nodo)   = trav2Items Items dcl0 Items1→2

```

Figure 3: Strict Compiler.

## 4 Further Optimizations

When looking at the functions of figure 3 we see that some of them do very little work. In this section we show how, after unfolding some definitions, some functions may be removed from the program.

### 4.1 Unfolding Redundant Data Types

Observe that neither the lazy nor the strict version of our compiler do compute any value when traversing nodes of type *Items*. They only pass arguments and results. We will now statically transform the program, preserving its semantics, in order to avoid these unnecessary steps in the computation. More efficient programs are obtained if we unfold the definition of data type *Item*:

```

data Program = P Items
data Items   = Cons_Item_Block Items Items
              | Cons_Item_Use   Name Items
              | Cons_Item_Decl  Name Items
              | NilItems
data Name    = Ident STR

```

and then write the corresponding functions. The bindings for the strict program are also simplified:

```

data Items1→2 = NilItems1→2 Int -- type(nodo)
              | Cons_Item_Block1→2 Int Items1→2 -- type(lev)

```

Consider the functions `trav1Item` and `trav2Item` applied to `Use` and `Decl` respectively. The compiler does not perform any computation when traversing `Use` nodes, since only in the second traversal the `uses` are processed. The same holds for `Decl` nodes in the second traversal. In this traversal the program is only computing the code and no declarations are collected in the environment anymore. So, instances of such nodes can be removed from the tree for the first and second traversal respectively. This can be achieved if we use different representations of the tree for different traversals, i.e., if we *split* the tree.

## 4.2 Splitting

A *split tree*  $T$  is a tuple  $[T_1, \dots, T_n]$  of terms, where  $n$  is the number of traversals performed on  $T$ . Term  $T_v$  includes only that part of  $T$  that is actually inspected during traversal `travvT`, with  $1 \leq v \leq n$ .

In our example nodes of type *Items* are traversed twice, inducing the *split data type*  $Items_s = (Items_1, Items_2)$ . The complete splitted data types are:

```

data Program1 = P1 Items1 Items2
data Items1  = NilItems1
              | Cons_Item_Decl1 Name Items1
              | Cons_Item_Block1 Items1
              | Cons_Item_Use1 Items1
data Items2  = NilItems2
              | Cons_Item_Decl2 Items2
              | Cons_Item_Block2 Items2 Items1 Items2
              | Cons_Item_Use2 Name Items2

```

Note that the data type *Name* is only included in the type constructor `Cons_Item_Decl1` for the first traversal and in the `Cons_Item_Use2` for the second one. In the other traversals it is not needed. The constructor `Cons_Item_Block2` has three children: the first one defines the tree for second traversal (which contains the block) and the other two define the two traversals to the body of the block.

Next we present the functions that split the tree according to the previous data types.

```

splitProgram (P Items) = (P1 Items1 Items2)
  where (Items1, Items2) = splitItems Items
splitItems (Cons_Item_Decl Name Items2) = (Cons_Item_Decl1 Name Items12, Cons_Item_Decl2 Items22)
  where (Items12, Items22) = splitItems Items2
splitItems (Cons_Item_Use Name Items2) = (Cons_Item_Use1 Items12, Cons_Item_Use2 Name Items22)
  where (Items12, Items22) = splitItems Items2

```

The traversal functions must be changed in order to use the split data types. A pattern `p(⋯)` selecting an alternative function is changed to the pattern `pv(⋯)`. A recursive call to a complete tree `travvT T` is mapped into a recursive call to a split tree `travvT Tv`. For example, the split version of the function applied on `P1` is:



```

trav1Program (P1 Items1 Items2 = (code)
  where (dclo, Items1→2) = trav1Items Items1 Emptyenv 0 0
          (code, nodo)      = trav2Items Items2 dclo Items1→2

trav1Items (Cons_Item_Use1 Items1) dcli nodi lev = (dclo, Items1→2)
  where (dclo, Items1→2) = trav1Items Items1 dcli nodi lev

```

### 4.3 Elimination

As a result of splitting an important optimization can be performed: the elimination of some data types and some *redundant* functions consisting of copy rules only. Consider the function **trav<sub>1</sub>Items** presented above, this function does not perform any useful computation. It directly passes arguments and results to a recursive call to itself. The split version of the strict program contains two redundant functions: the alternatives applied to the split data type constructors **Cons\_Item\_Decl**<sub>1</sub> and **Cons\_Item\_Use**<sub>2</sub>. Thus, these alternatives can be eliminated. Nodes that are instances of those type constructors can be eliminated too. Elimination requires three steps:

1. First the redundant type constructors are eliminated;
2. Second the split functions are transformed in order to deal with the fact that nodes that are instances of such constructors have disappeared.

In the running example the transformed split functions are:

```

splitItems (Cons_Item_Decl Name Items2) = (Cons_Item_Decl1 Name Items12, Items22)
  where (Items12, Items22) = splitItems Items2
splitItems (Cons_Item_Use Name Items2) = (Items12, Cons_Item_Use2 Name Items22)
  where (Items12, Items22) = splitItems Items2

```

3. Finally, the redundant functions are eliminated.

Observe that, without the unfolding of the *Item* data type the copy operations were hidden, that is, the program would need to pattern-match nodes of type *Item* in order to know which particular instance it was.

Although we have presented the splitting and elimination as transformations of the program and the associated tree structures, our system actually generates code which directly constructs the splitted and contracted trees.

## 5 Attribute Grammars

We have developed a system which performs the global analysis described in section 3 and the splitting and elimination optimizations. The programs are specified by an attribute grammar and the strict functional programs are automatically generated. The bindings, the split data types and the split functions are induced by the attribute grammar too.

We have implemented a generator for the construction of incremental evaluation of attribute grammars. This generator uses the techniques from this paper. Experience shows that large functional programs can be efficiently implemented with our techniques. The generator is bootstrapped: it generates itself from a rather large specification. The original program has 90 traversal functions that work on data types which together have 307 different constructors.

The transformed program consists of 866 sub-traversal functions which require 2188 binding constructors. Some traversal functions are transformed in as many as 12 sub-traversals.

## 5.1 Attribute Evaluator

We have incorporated a new back-end to the LRC system [Pen94] in order to produce GOFER based evaluators. The code presented in figure 4 has been automatically generated by our system, starting from the attribute-grammar-equivalent of the initial circular program. In order to stick with our GOFER-based presentation we have only replaced some semantic functions by their GOFER equivalents.

```

trav1Program (P1 Items1 Items2) = (Program.code)
  where (Items.dclo, Items1→2) = trav1Items Items1 Emptyenv 0 0
        (Program.code, Items.nodo) = trav2Items Items2 Items.dclo Items1→2

trav1Items (NilItems1 ) Items.dcli Items.nodi Items.lev = (Items.dcli, NilItems1→2 Items.nodi)

trav1Items (Cons_Item_Decl1 Name Items12) Items.dcli Items.nodi Items.lev = (Items.dclo, Items1→2)
  where (Items2.dclo, Items1→2) = trav1Items Items12 Items.dcli (Items.nodi + 1) Items.lev
        Items.dclo = Consenv Name Items.lev Items.nodi Items2.dclo

trav1Items (Cons_Item_Block1 Items13) Items.dcli Items.nodi Items.lev =
(Items.dclo, Cons_Item_Block1→2 (Items.lev + 1) Items1→2)
  where (Items.dclo, Items1→2) = trav1Items Items13 Items.dcli Items.nodi Items.lev

trav2Items (NilItems2 ) Items.env (NilItems1→2 Items.nodo) = ([], Items.nodo)

trav2Items (Cons_Item_Use2 Name Items22) Items.env Items1→2 = (Items.code, Items.nod)
  (Items2.code, Items.nodo) = trav2Items Items22 Items.env Items1→2
  Items.code = [access Items.env Name] ++ Items2.code

trav2Items (Cons_Item_Block2 Items23 Items12 Items22) Items.env (Cons_Item_Block1→2 Items22.lev Items1→2) =
(Items.code, Items.nodo)
  where (Items3.code, Items.nodo) = trav2Items Items23 Items.env Items1→2
        (Items2.dclo, Items1→2) = trav1Items Items12 Items.env 0 Items2.lev
        (Items2.code, Items2.nodo) = trav2Items Items22 Items2.dclo Items1→2
        Items.code = [Enter Items2.nodo] ++ Items2.code ++ [Leave Items2.nodo] ++ Items3.code

```

Figure 4: Splitted Compiler.

## 5.2 Incremental Behaviour

In next table we present results of two different incremental reevaluations of the example sentence (see section 2): one modification of the last **use** statement in the global block into **use** *w* and one modification of the declaration **decl** *w* into **decl** *u*. Both reevaluations started in a state where all functions applied when processing the initial sentence were stored in the cache.

```

Items = Cons_Item_Decl Name Items2
      | Cons_Item_Use Name Items2
      | Cons_Item_Block Items2 Items3
      | NilItems
      Items.used = Consuse(Name, Items2.used)
      Items.used = Items2.used
      Items2.dcli = project(Items.env, Items2.used)
      Items.used = Items3.used
      Items.used = Emptyuse()

```

Figure 5: Attribute Grammar notation.

Modification	Strict Compiler of fig. 3		Splitted Compiler of fig. 4	
	<i>Hits</i>	<i>Misses</i>	<i>Hits</i>	<i>Misses</i>
Change global <b>use</b> :	6	15	6	5
Change global <b>decl</b> :	3	25	3	15

When processing the first modification the *splitted* compiler has a better behaviour since it does not need to reevaluate the declarations. Modifying a global variable usually has a poor incremental behaviour, since all the environment change. Both evaluators only reuse 3 functions and have to recompute most of the functions. The difference in the number of misses are due to the absence of calls to eliminated functions.

In our example however the nested block does not use that changed global variable at all. Nevertheless, since its total environment has changed, all the functions applied to process that block are recomputed. We can easily write an AG dealing with this problem by letting each block synthesize a list of those variables which actually occur in a **Use** constructor and project the environment on that list. This is easily achieved by adding the following attribution rules to the AG as presented in figure 5.

Where the type of the attribute *used* is a list of *Names* and **project** is a simple semantic function which implements the projection.

In the table below we present the results of the *splitted* evaluator using such a projection. The resulting splitted evaluator is a 3 visit-evaluator.

Modification	<i>Hits</i>	<i>Misses</i>
Change global <b>use</b> :	8	5
Change global <b>decl</b> :	7	10

When reevaluating the second modification the number of misses decreases and the number of hits increases. The nested block is reevaluated without recomputing any visit-function. It reuses all three functions: the one that synthesizes the list of used variables, the one that synthesizes the declarations and the one that synthesizes the code.

Note that this efficient program transformation was performed without changing any recursive function. The attribution rules presented above were added to the AG using its natural structural decomposition.

## 6 Conclusions

This paper presented a transformation from lazy into non-lazy ones. A function is transformed into one or more functions that must be called in sequence. Extra data types and

arguments are added to the non-lazy functions when values computed in one function are needed in another. Measurements show that the transformed and optimized functions can be executed incrementally with a function cache. The techniques can be used to combine several catamorphisms on mutual recursive data types.

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