

2007/2008 Graphics Tutorial 3

Problem 1 Let the following planes in \mathbb{R}^3 be given:

- $V_1 : 3x + 2y + z = 10$
- $V_2 : 2x + y + 3z = 13$
- $V_3 : x + 3y + 2z = 13$

1. Compute the coordinates of the intersection point p of the three planes with Gaussian elimination. Check that p indeed satisfies all three plane equations.
2. Express each coordinate of p as a fraction of two determinants, and work out the x coordinate.

The system of linear equations of the above problem has a unique solution. Other systems may have no solutions at all, or an infinite number of solutions. In the next problem, we consider a system that has no solutions (such a system is called *inconsistent*):

Problem 2 Let the following planes in \mathbb{R}^3 be given:

- $V_1 : 3x + 2y + z = 10$
- $V_2 : 6x + 4y + 2z = 26$
- $V_3 : x + 3y + 2z = 13$

1. What is the geometric interpretation of the (empty) set of solutions of this system?
2. What happens if we try to solve this system with Gaussian elimination?
3. We can write the system in matrix notation as $Ax = b$. What is the determinant of A in this case?

In the next problem, we consider a system that has an infinite number of solutions:

Problem 3 *Let the following planes in \mathbb{R}^3 be given:*

- $V_1 : 3x + 2y + z = 10$
- $V_2 : 6x + 4y + 2z = 20$
- $V_3 : x + 3y + 2z = 13$

1. *What is the geometric interpretation of the set of solutions of this system?*
2. *What happens if we try to solve this system with Gaussian elimination?*
3. *We can write the system in matrix notation as $Ax = b$. What is the determinant of A in this case?*
4. *Although we “get stuck” with Gaussian elimination, we can get the matrix in upper diagonal form: this is a situation where the matrix (or more precisely, the left (square) part of the augmented matrix) only has non-zero entries on or above the diagonal. We can use this to find a parametric equation that satisfies the three plane equations. In our case, for example, we could state $z = t$, and work our way up the matrix to find y and x expressed in the parameter t as well. Use this technique to find a parametric equation for the line that is the intersection of the three planes.*

Problem 4 *A matrix is orthogonal if all column vectors are mutually perpendicular. A matrix is orthonormal if it is orthogonal and all column vectors have unit length.*

Show that the inverse of an $n \times n$ orthonormal matrix is its transpose. Hint: show that for a 2×2 matrix A , we have $A^T A = I$, and then generalize.